

# Solar Tracking Structure Design

## Project Proposal

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# Presentation Overview

- Introduction
  - Problem and Customer Definition
  - Needs and Requirements
- Concept Generation and Selection
  - Decision criteria
- Engineering Analysis
- Cost Analysis
- Schedule
- Conclusion

# Problem and Client Definition

- Design an all-seasonal solar tracking device.
- Dr. Acker
  - Professor of Mechanical Engineering at Northern Arizona University (NAU)
  - Director of NAU Sustainable Energy Solutions Group

# Needs and Project Goal

- Needs
  - Reliable
  - Inexpensive
  - Easily maintainable
  - Efficient while successfully tracking the sun
- Project Goal
  - Design a solar tracking system that will efficiently convert solar energy to useable energy.

# Objectives

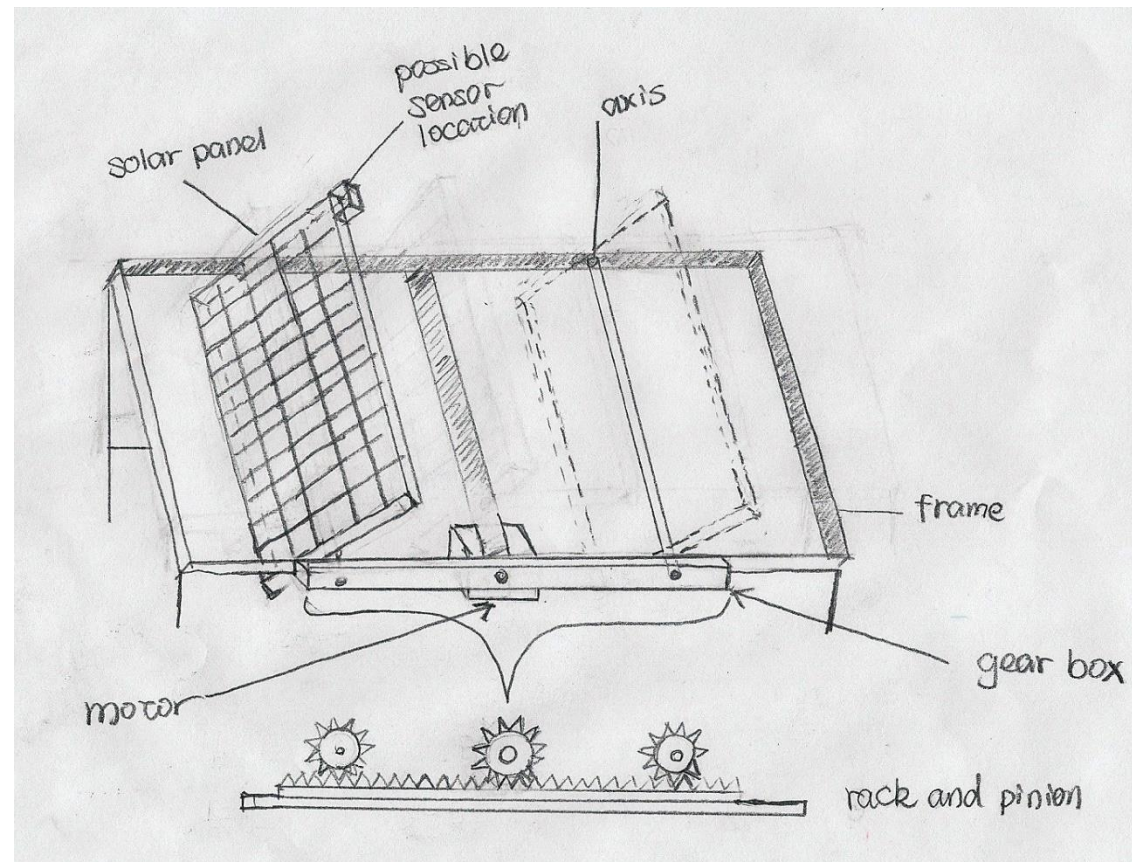
Objectives	Measurement Basis	Units
Inexpensive	Unit cost of production	\$
Efficiency	Useable amperage generated	$\text{amp}/\text{hour}$
Low Maintenance	Time until first part replacement	days
Manufacturability	Amount of moving parts	Number of parts
Build Quality	Stress vs. Strain	$N/m^2$
Snow Shedding Ability	Area without snow	$m^2$

# Operating Environment

- Utilize MATLAB to run the program
  - Deliver power to actuators
  - Transfers motion to the solar panels for tracking
- Electronic equipment might be affected by voltage/amperage drops within cables
- Mechanical equipment may be affected by inclement weather, such as snow, clouds, and dirt
- Voltage readers will be connected at the outputs to measure actual efficiency

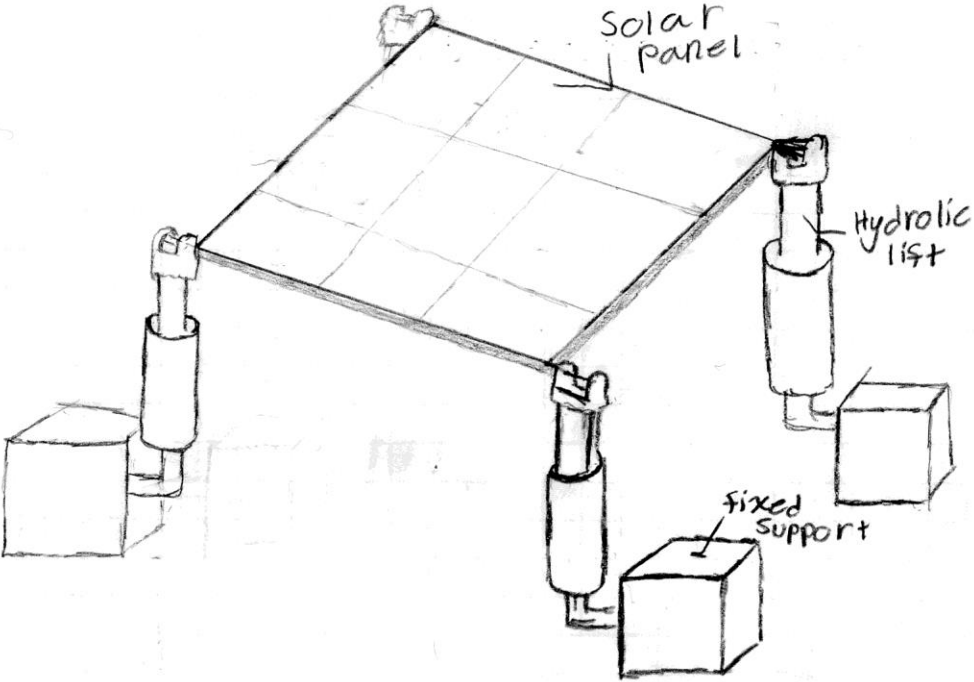
# Solar Panel Array

Rack and pinion system with multiple panels



# Hydraulic Design

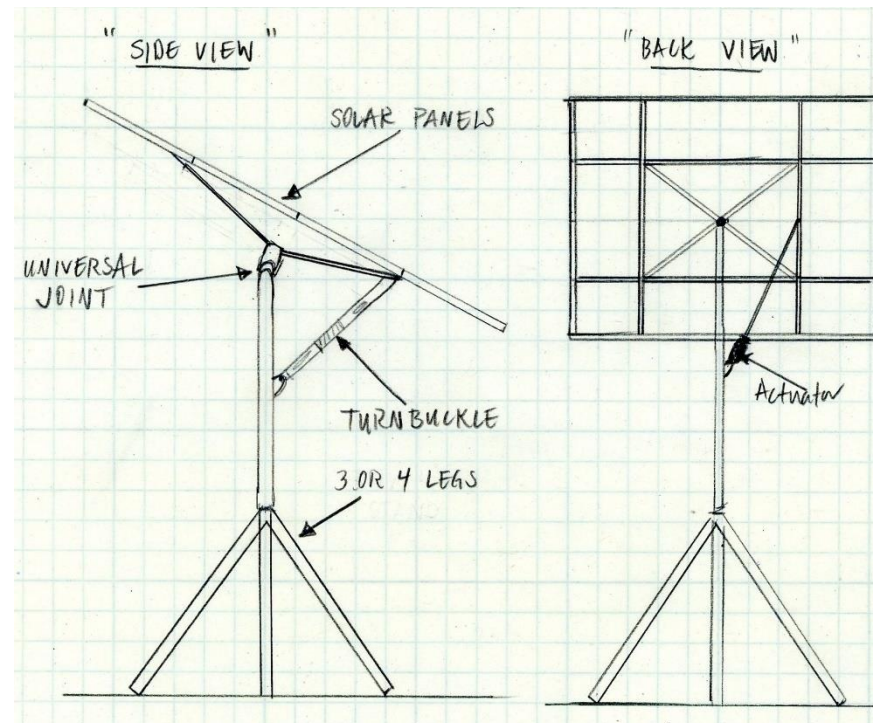
Solar pane is moved by hydraulic





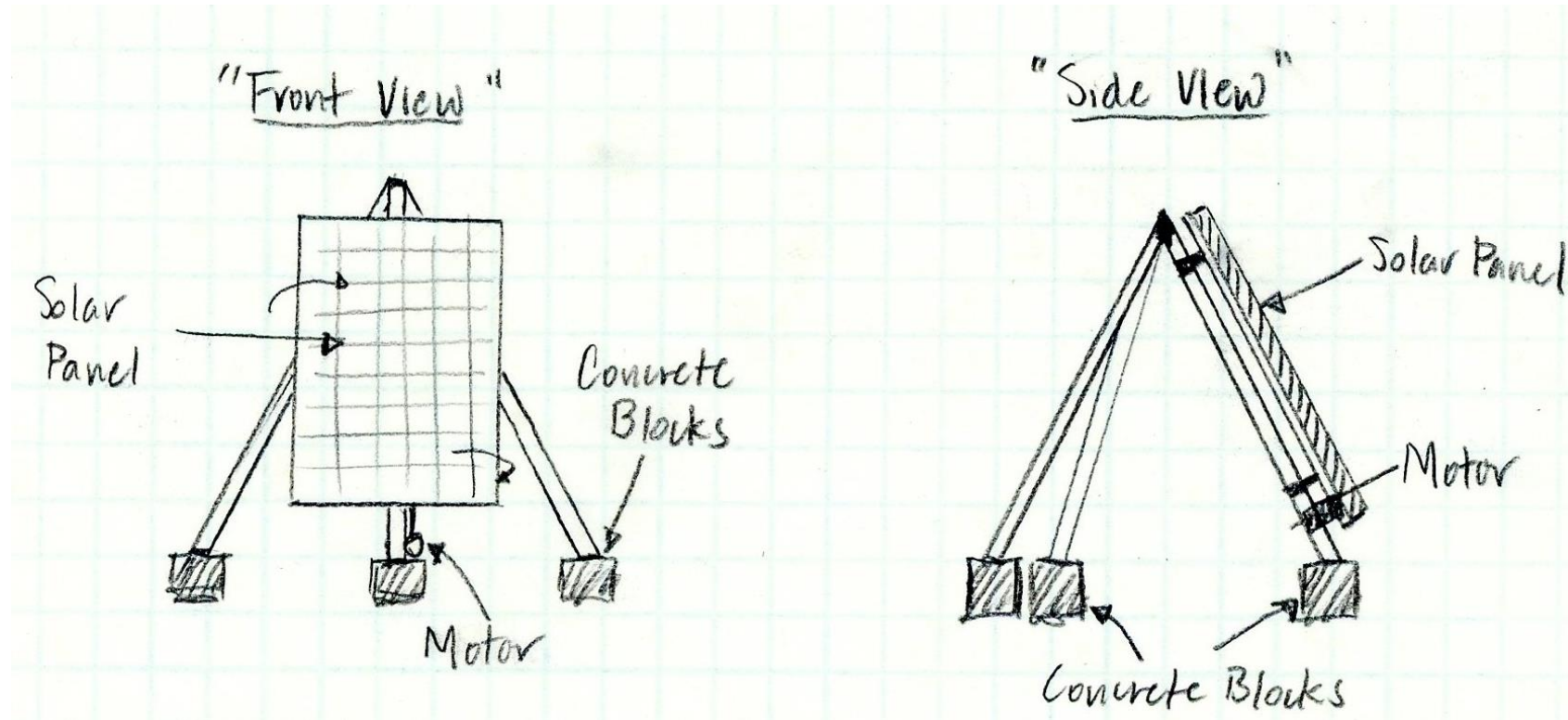
# Standing Tripod Design

Simple tripod that is easy to move



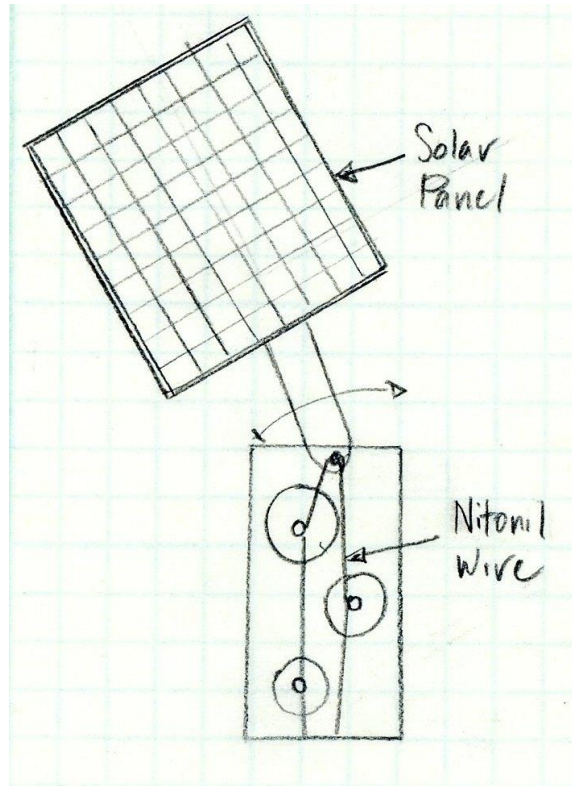
# Angled Solar Tracker

Tripod design with panels on leg



# Nitinol Solar Tracker

Pulley system with Nitinol cable



# Category Factor Weights

Lightweight=1

- Self-imposed

Survivability=2

- Designed for all weather

Maintenance=3

- Client wants low maintenance system

Safety=4

- Unsafe design could short circuit, fall apart during maintenance, etc.

Efficiency=5

- Current designs inefficient

Cost=6

- Current designs are expensive

Reliability=7

- Dr. Acker emphasized this objective

# Concept Decision Matrix

	<u>Safety</u>	<u>Cost</u>	<u>Light weight</u>	<u>Efficiency</u>	<u>Maintenance</u>	<u>Reliability</u>	<u>Survivability</u>		
<u>Weighted Importance</u>	4	6	1	5	3	7	2		<u>Total</u>
<u>Designs</u>									
Half cylinder	0	-1	-1	1	0	0	1		0
Angled tracker	1	1	0	1	1	1	1		27
Solar array	1	1	0	1	0	1	1		24
Hydraulic	1	0	1	1	1	1	1		22
Nitinol tracker	1	-1	1	0	1	1	1		11
Water low tech	0	1	-1	0	-1	0	1		4
Standing tripod	0	1	1	1	1	1	0		22

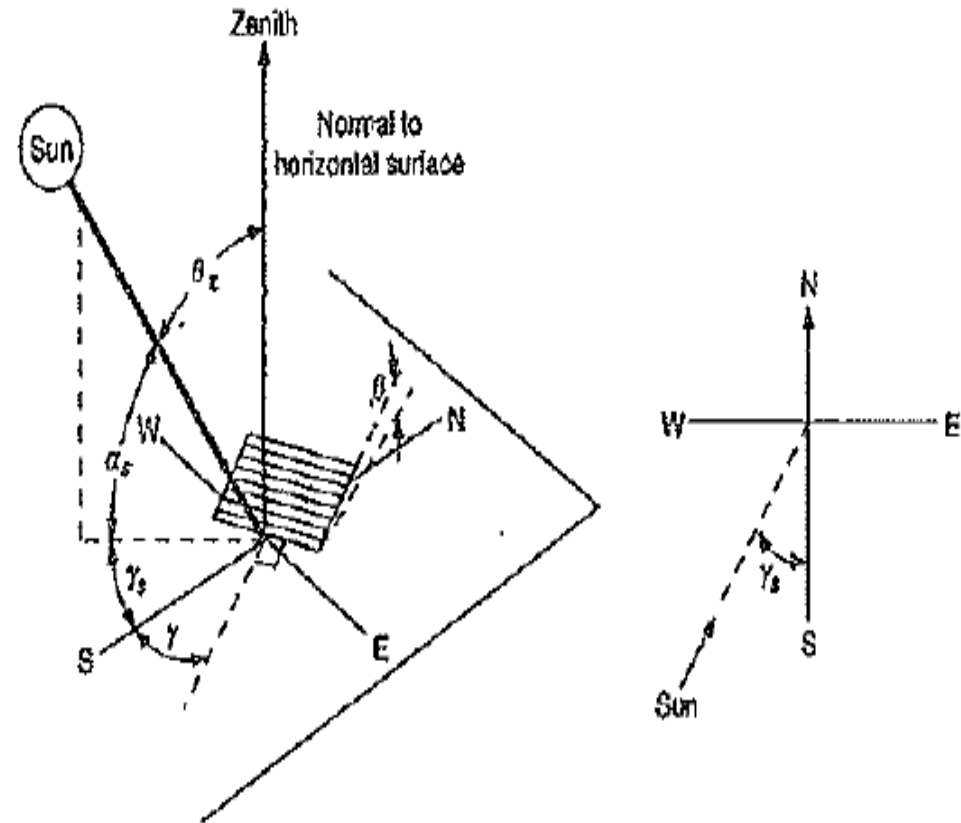
# Engineering Analysis Overview

- Three concepts selected from concept generation
- Analysis of solar tracking angles
- Static analysis of the designs
- Final concept

# Solar Tracking Angle Analysis

- Most important angles
  - Solar azimuth ( $\gamma_s$ )
  - Angle of Incidence ( $\Theta$ )
  - Panels slope angle ( $\beta$ )
- Tracking systems are supposed to
  - Minimize angle of incidence ( $\Theta$ )
  - Maximize angle of incident beam radiation

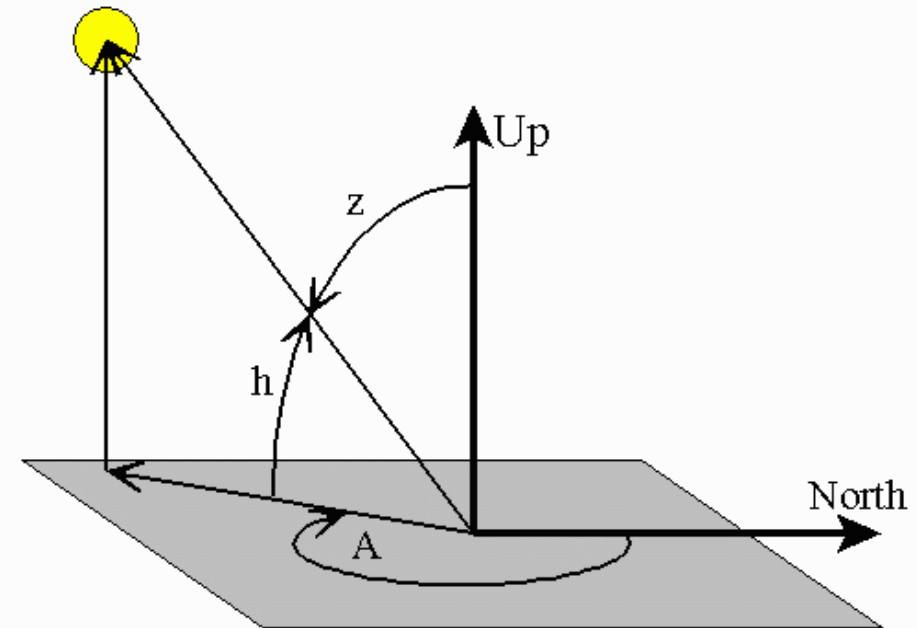
All angles required for analysis



# Solar tracking Analysis cont.

- Location
  - Flagstaff at latitude of 35 degrees North
  - Fixed slope angle of 36 degrees
- Matlab Program
  - Based on desired day of the year
  - $\theta$  (angle of incidence)
  - $\gamma_s$  (Azimuth angle)
  - $\theta_z$  (Zenith angle)

North-South Axis slope tracking



$h$  = elevation angle, measured up from horizon

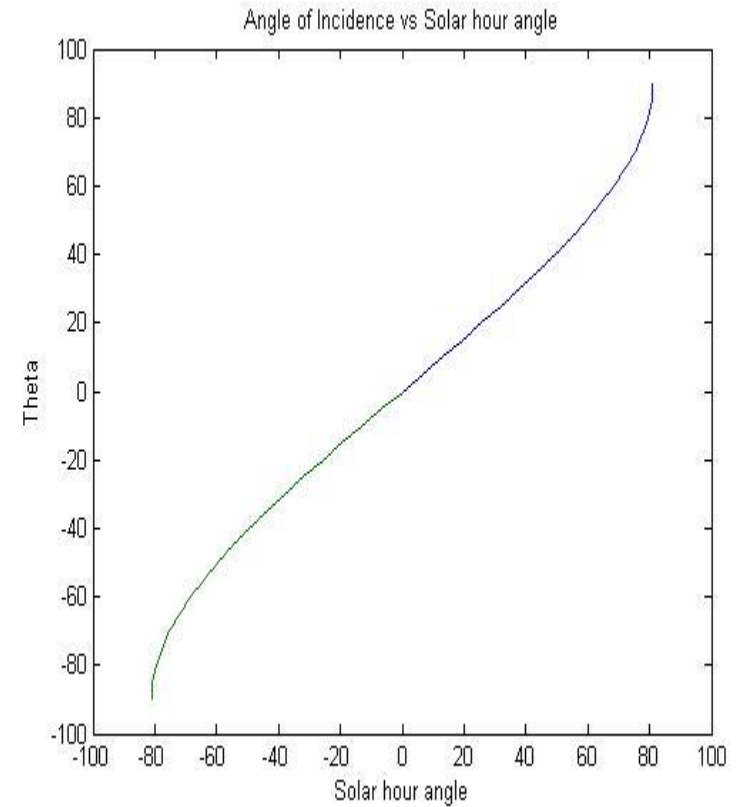
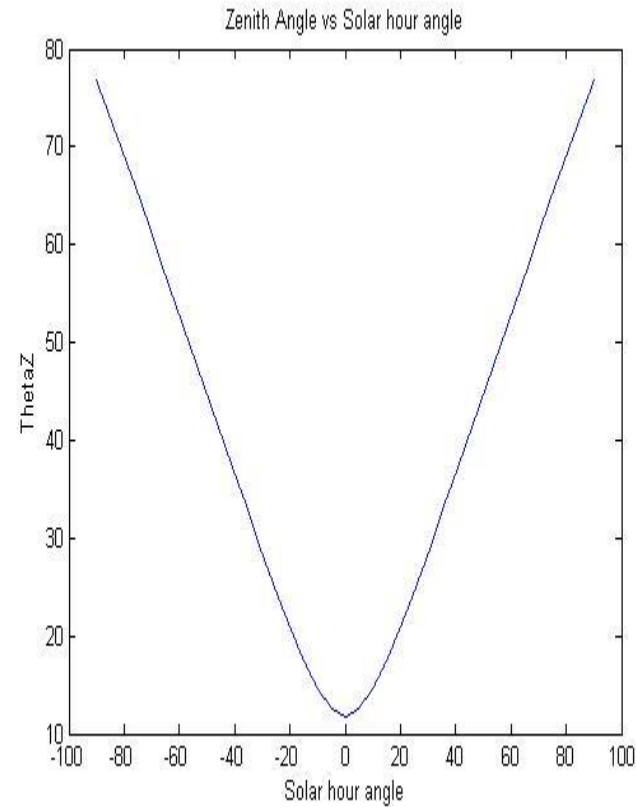
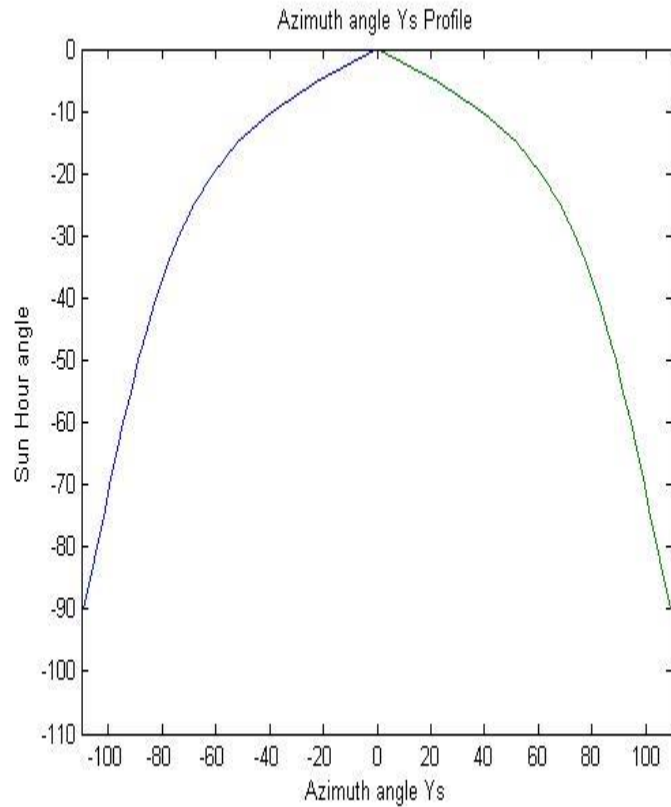
$z$  = zenith angle, measured from vertical

$A$  = Azimuth angle, measured clockwise from North

[http://capsis.cirad.fr/capsis/help\\_en/samsaralight](http://capsis.cirad.fr/capsis/help_en/samsaralight)

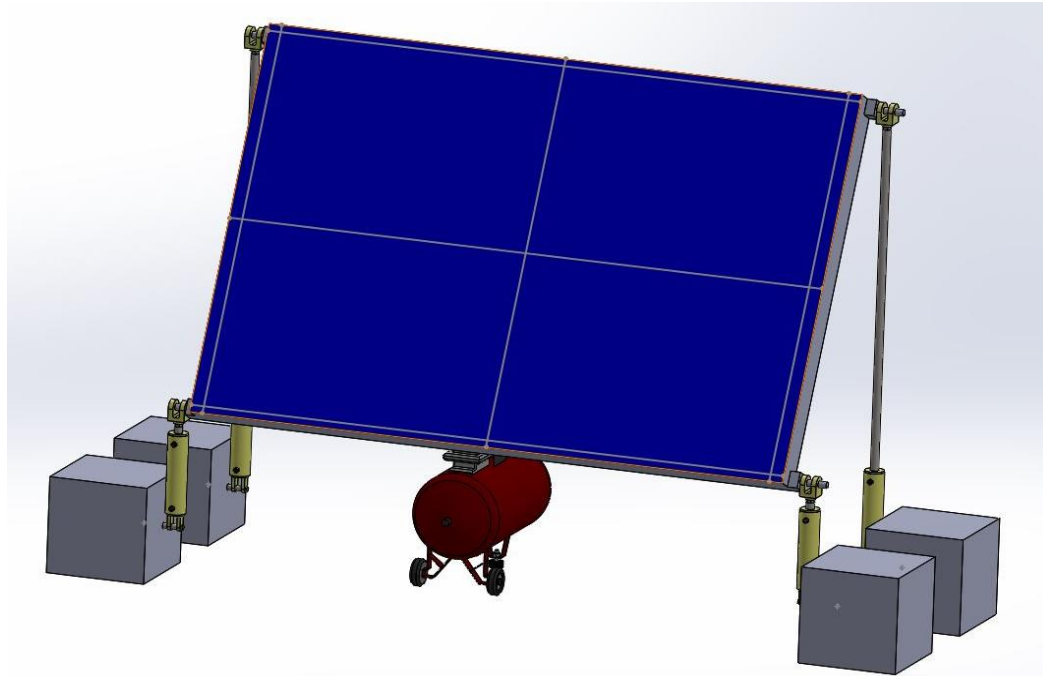


# Solar tracking Data

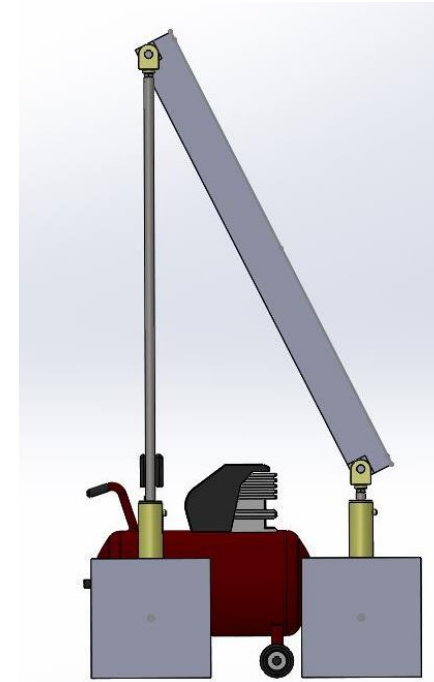


# Hydraulic Tracker Design

Isometric view

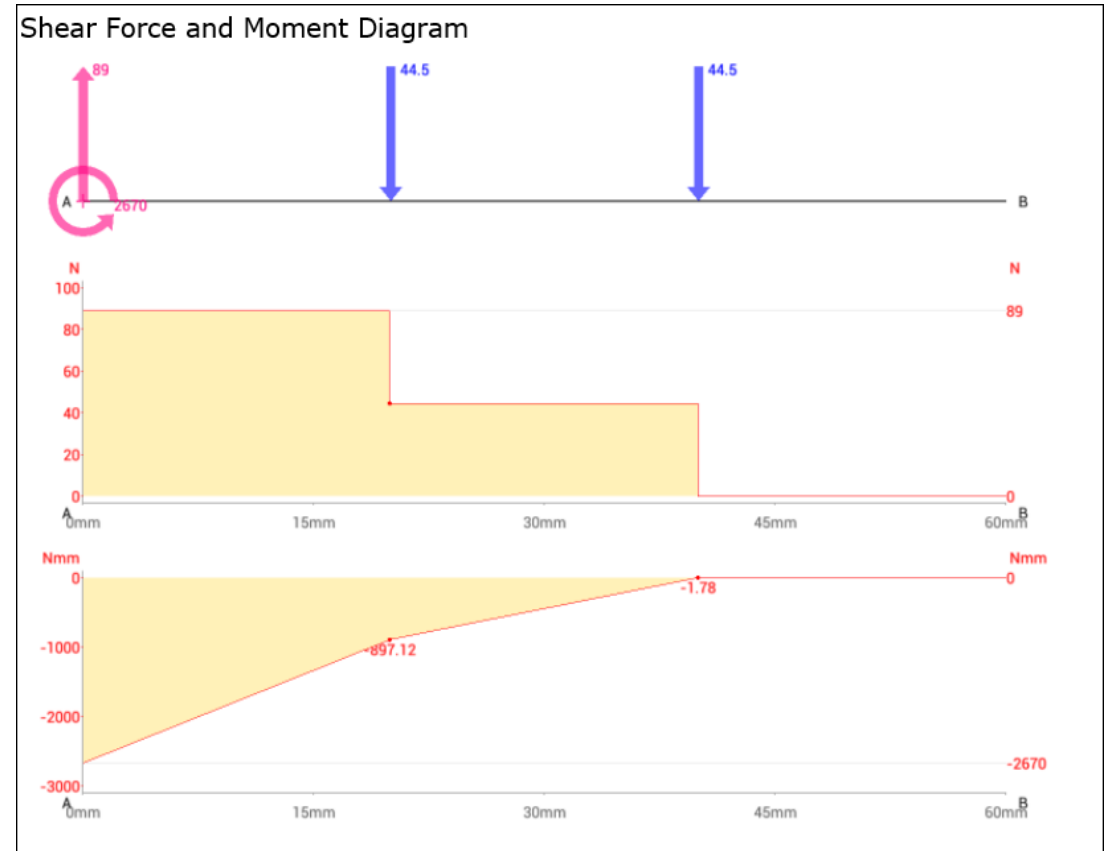


Side view



# Analysis

- The weakest point is the connection between the hydraulic and concrete blocks
- The force is 88.97 N
- Moment 2.67 N-m

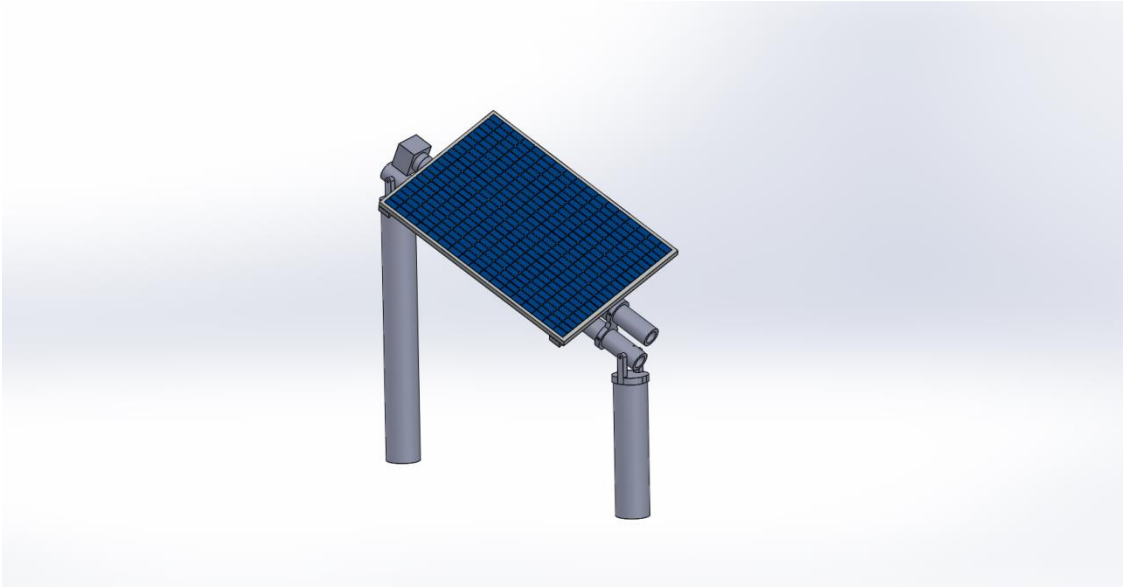


# Part Selection

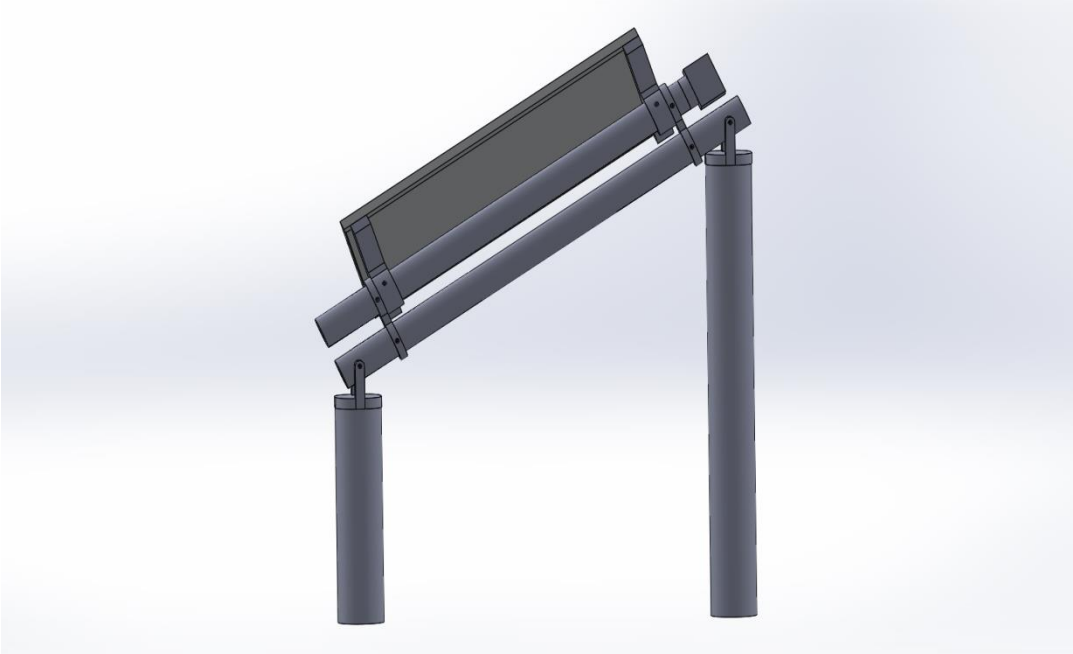
- Hydraulic
  - Piston diameter of 12.5 cm
  - Height difference is 1.045m
  - 49.1 kN of force
- Pump system
  - Produce 80 bars

# Angled Tracker Design

Isometric view

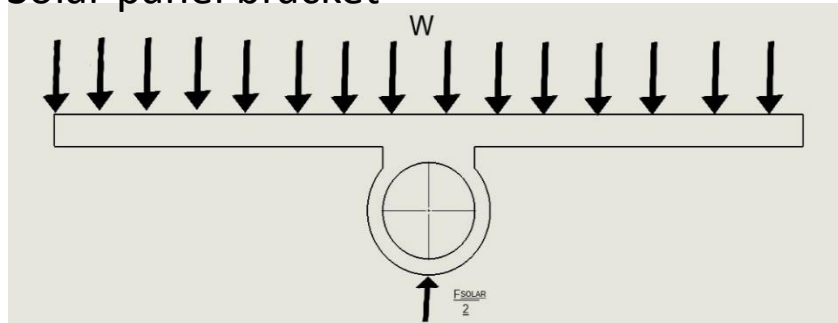


Side view

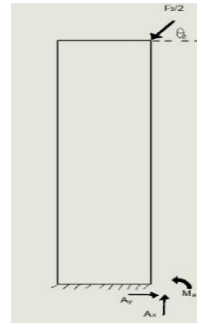


# Angled Solar Tracker Frame Analysis

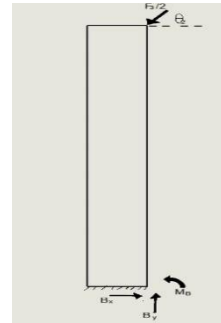
Solar panel bracket



Support 1



Support 2



## Forces Solved

$$F_{\text{solar}} = 325.4 \text{ N}$$

$$F_2 = 341.42 \text{ N}$$

$$F_3 = 357.44 \text{ N}$$

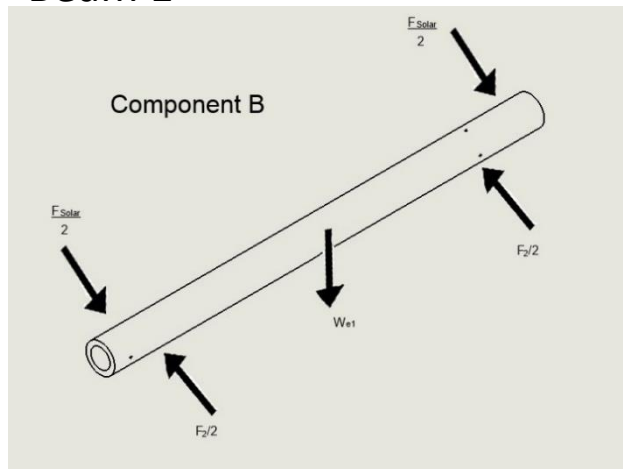
$$A_y = 64.34$$

$$A_x = 166.737$$

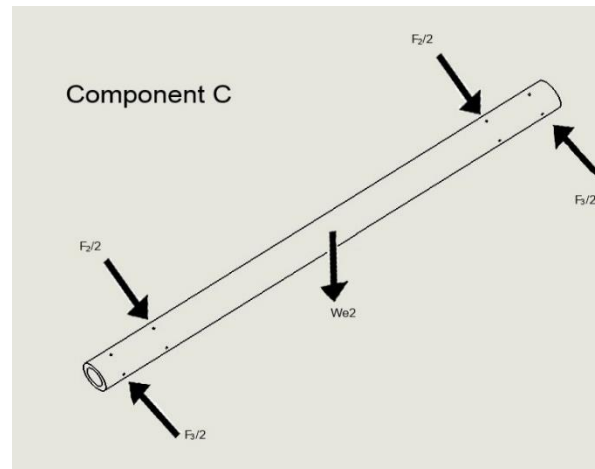
$$B_y = 64.34$$

$$B_x = 166.737$$

Beam 1



Beam 2



# Angled Solar Tracker Torque Analysis

- The Torque was calculated using :

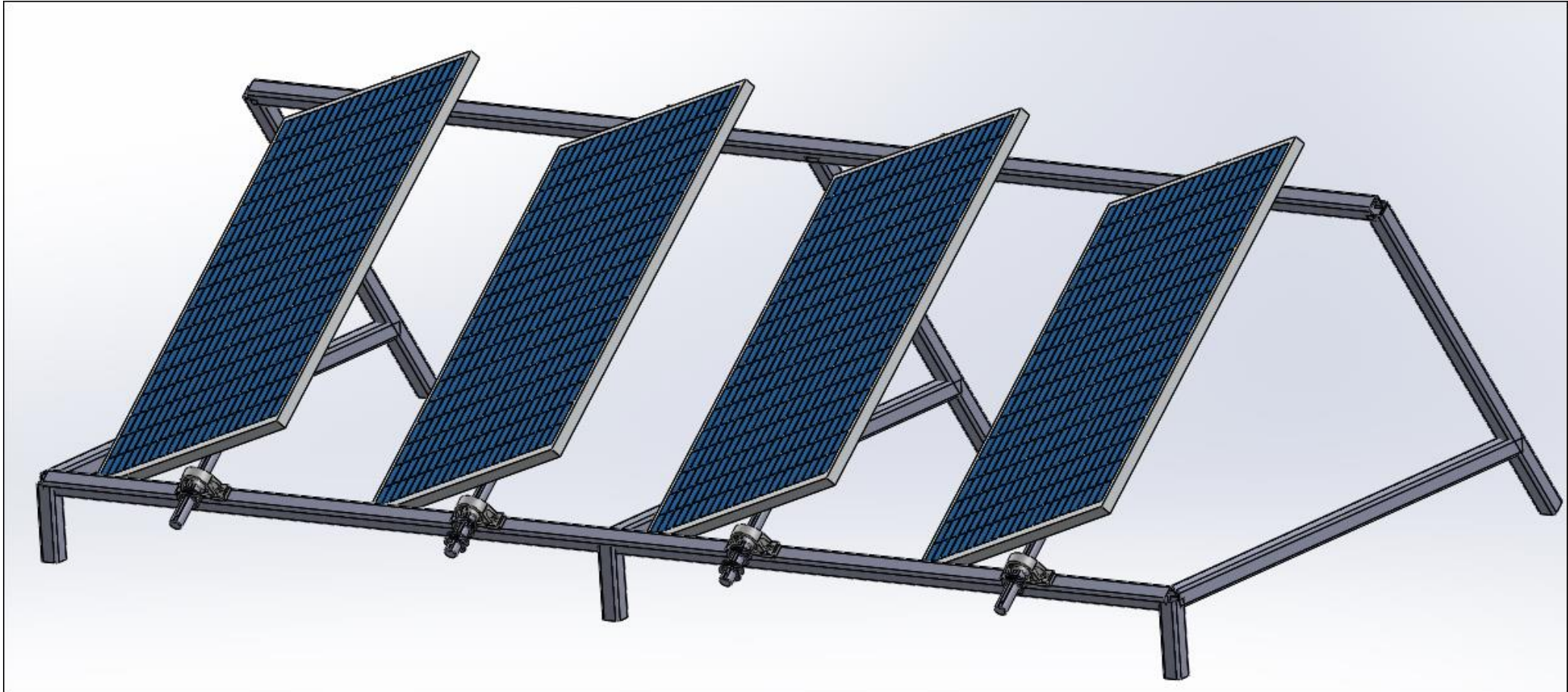
$$T = (F \times 0.48) \times r$$

- Torque = 6.5079 N\*m
- Finding the desired Motor using Full-load Torque equation

$$T = (HP \times 5252)/rpm$$

- HP/rpm = 0.001239

# Solar Array

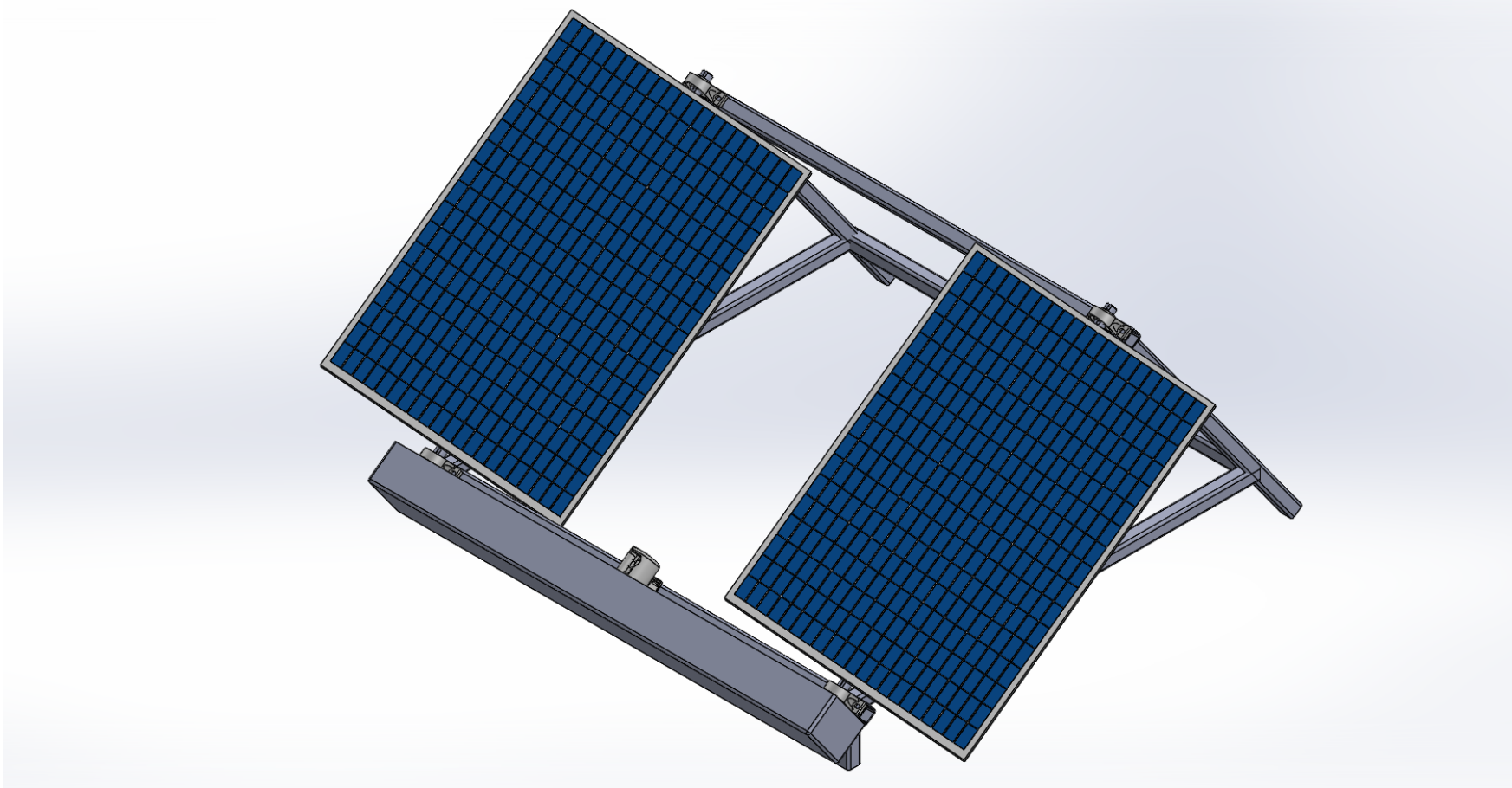




# Final design selection

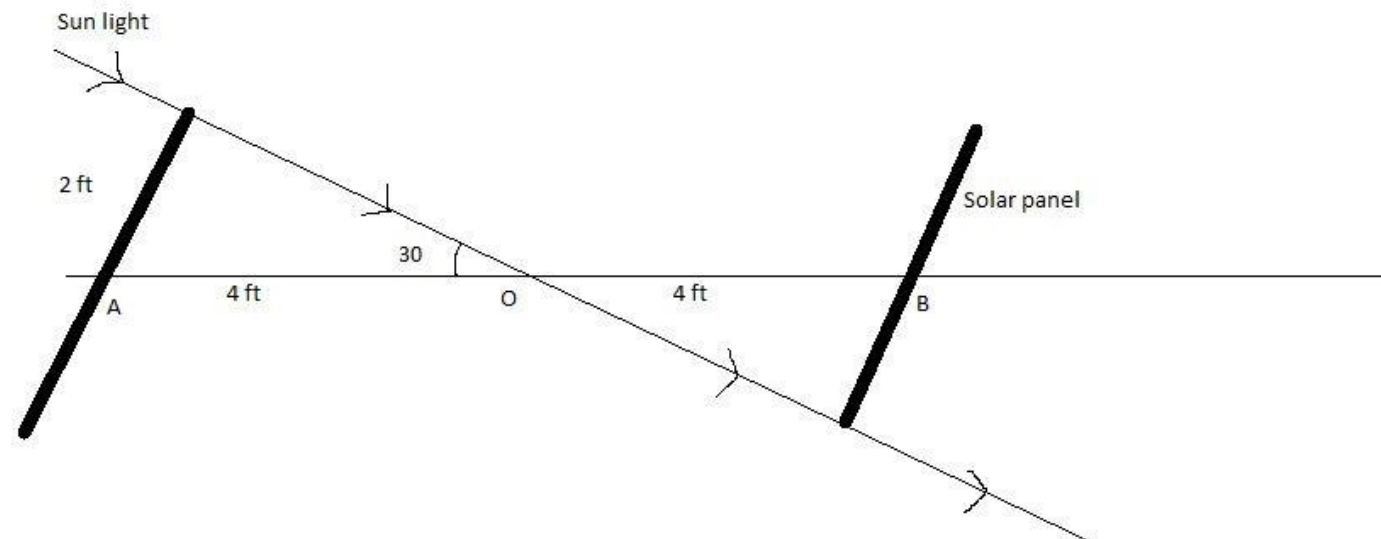
- Solar array
  - Holds two panels
  - Standard parts
  - More evenly distributed weight
- Angled tracker
  - Only holds one panel
  - Space may become an issue
- Hydraulic design
  - Unreasonable power requirements
  - Technical flaws
  - High operating cost

# Updated Design



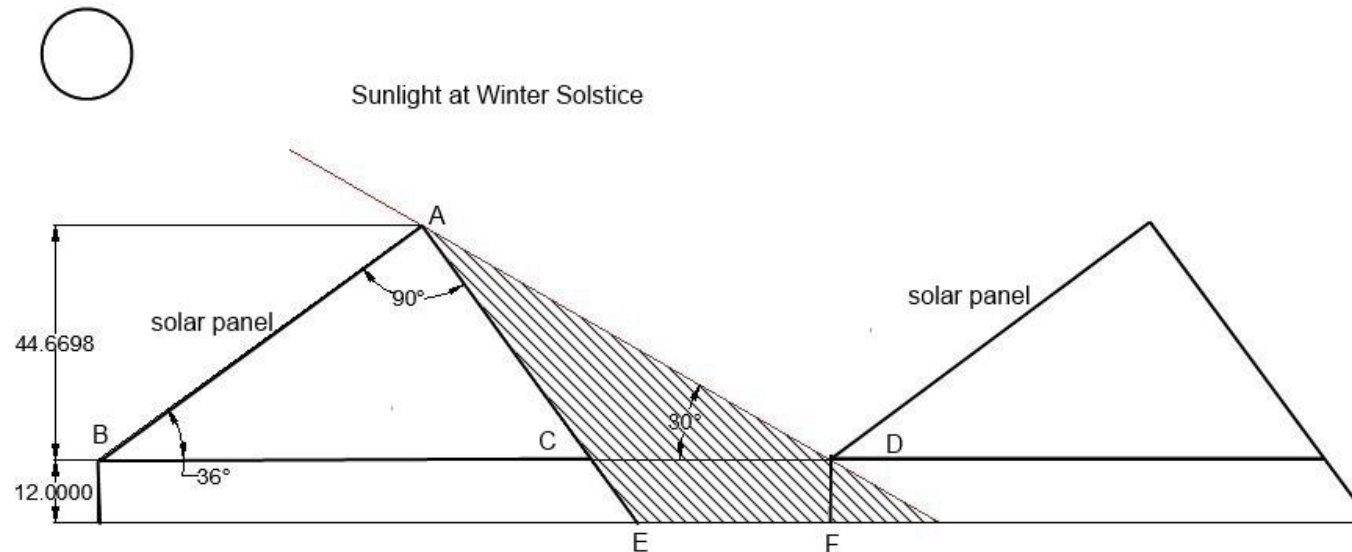
# Shading Analysis

The minimum space (AB) between two adjacent solar panels is 8 ft.



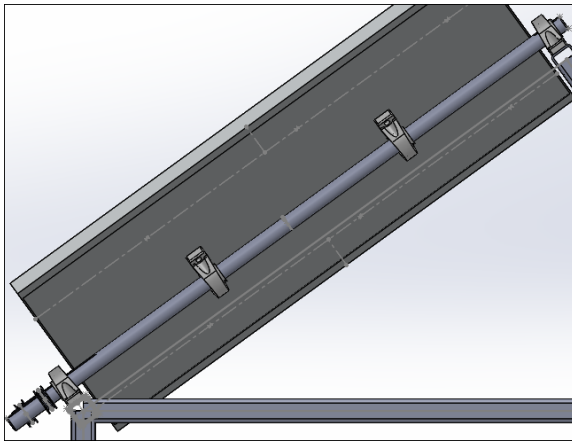
# Shading Analysis(Cont.)

- The minimum space (segment EF) between two adjacent solar tracker is 3.5 ft.

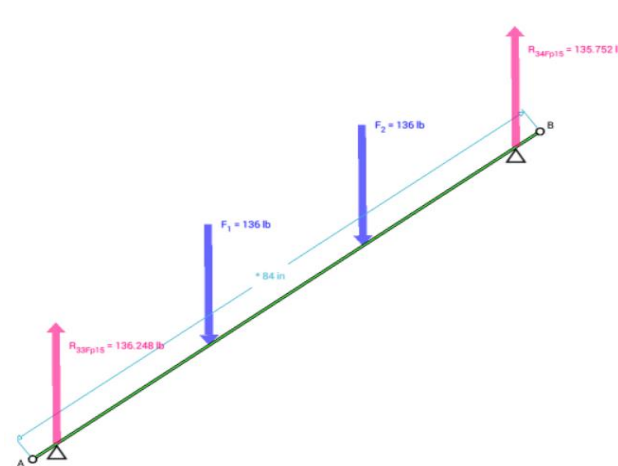


# Structure Analysis of solar panel array (Shaft)

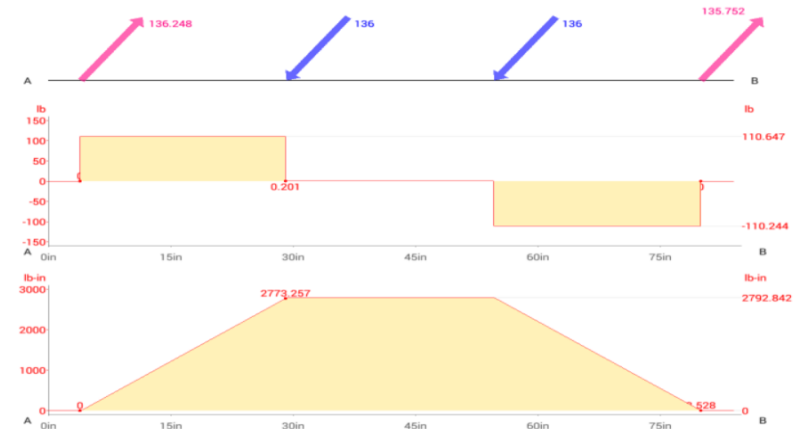
Side view of the solar panel



Free Body Diagram



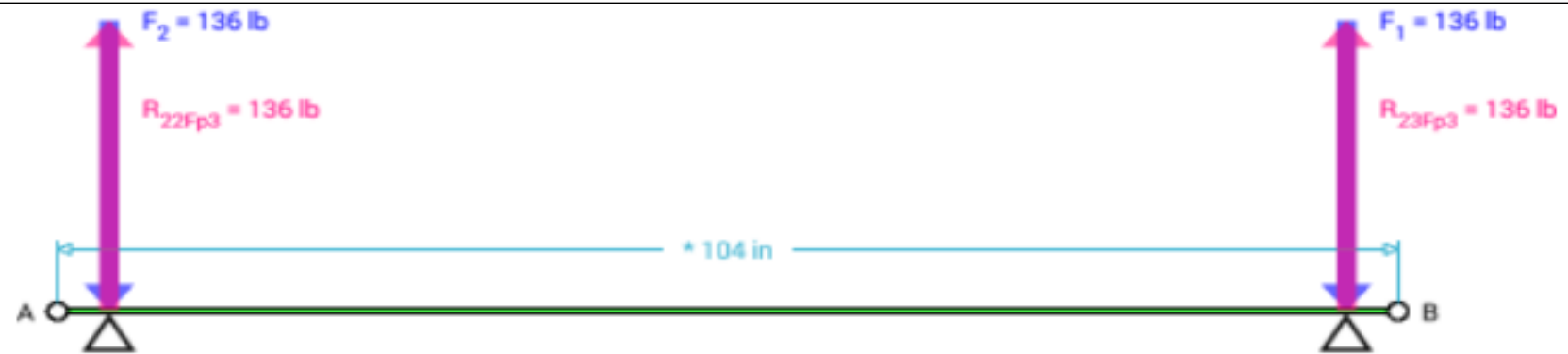
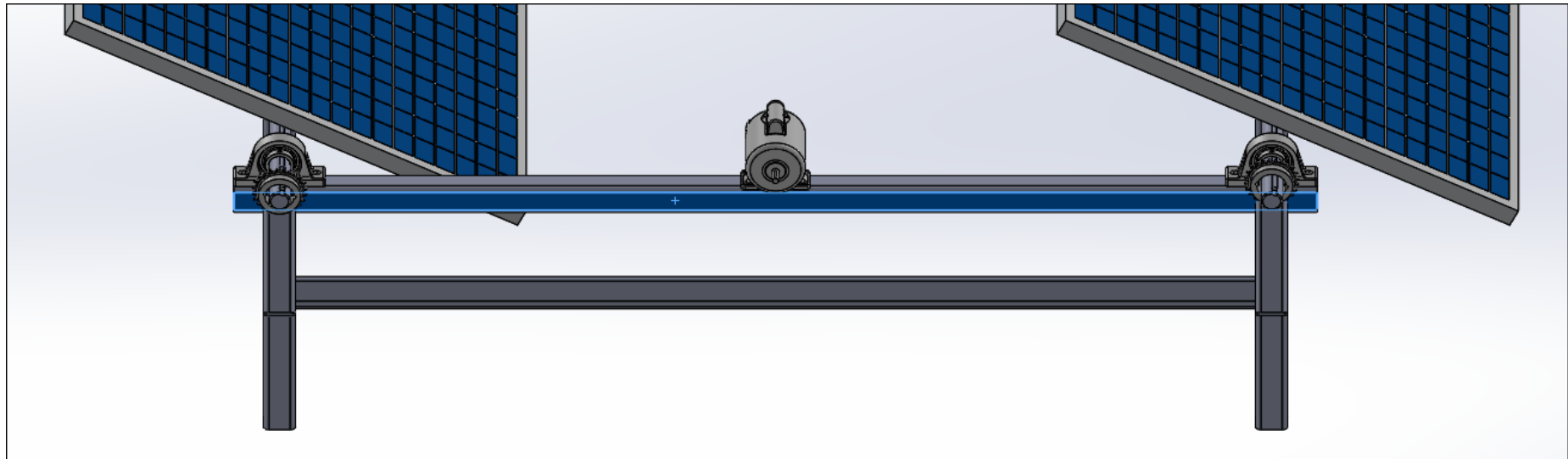
Shear and Moment Diagram



- The reacting force on each support (A and B) point is 136 lb.

- Fracture might occur between two support point (A and B)
- Maximum moment is 2774 lb-ft.

# Structure Analysis of solar panel array (Beam)



# Solar Panel Array Torque Analysis

- The Torque was calculated using :
  - $F_c = \mu \times W$        $\mu = 0.16$
  - $T = F_c \times D/2$        $D = 2 \text{ in.}$
  - $T = 43.52 \text{ lb-in}$
- Desired Motor using Full-load Torque equation
  - $T = (HP \times 5252 \times 8.851) / rpm$
  - $HP / rpm = 0.001872$

# Cost Analysis

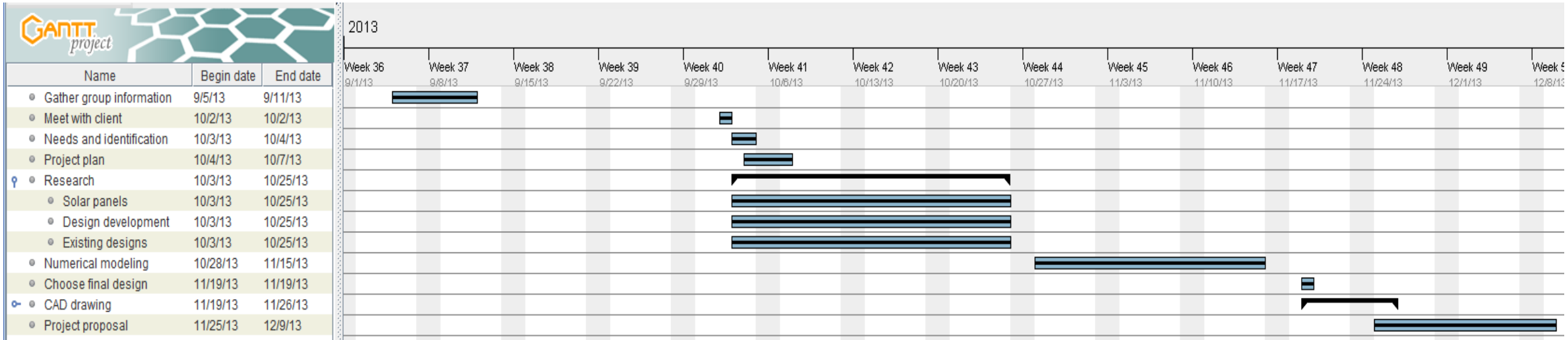
Parts	Company	Unit price	Amount	Total Cost	Shipping Cost (Ground)
3"×3"×0.25" Square tube	Bobco Metals	73.29/8ft	64ft	\$897.87	\$420.11
2" Shaft	Bobco Metals	110.91/8ft	2	\$221.82	\$132.42
2" pillow block bearings	BearingsOn.com	29.98	4	\$119.92	\$9.00
Gears	ZOROTools	36.05	4	\$144.20	\$8.00
Chain	RollerChain4Less	184.65/10ft	2	\$369.30	\$83.26
DC Motor, NEMA 56C, 90 VDC, 3/4 hp, 1750 rpm	Omega	318.00	1	\$318.00	\$8.00
Aluminum Flat sheet 12"×48" ×1//16"	Bobco Metals	21.21	4	\$84.84	\$20.27
Waterproofing Paint	Home Depot	114.98	5 gallons	\$114.98	\$0.00
Bolts	Home Depot	0.14	20	\$2.80	\$0.00
				<b>\$2270.98</b>	<b>\$681.06</b>



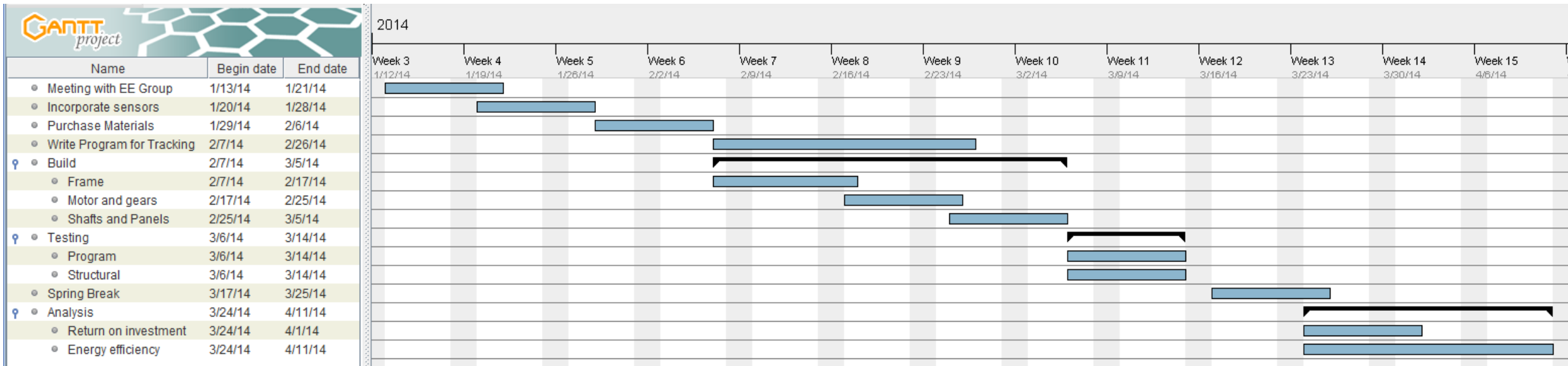
# Labor Costs

- Design will be built and assembled by team
- Micah, Anthony, Joshua all have welding experience
- Machine shop on campus will be used for welding

# Current Gantt Chart



# Spring Semester Gantt Chart



# Conclusion

- Problem description
  - Tracking the sun's movement increases efficiency of solar panels
  - Current solar tracking units are expensive
- Concept Generation and selection
  - Several different concepts generated
  - Evaluated concepts and chose three designs to evaluate in greater detail

# Conclusion Cont.

- Engineering Analysis
  - Determined stress concentrations
  - Evaluated shading
  - Calculated solar angels
- Cost Analysis
  - Evaluated the cost of the motor
  - Evaluated the cost of the structure

# References

- Beckman A., William, Duffie A. John, 2006, “Solar Engineering of Thermal Processes”, Third Edition, John Wiley & Sons, Hoboken, New Jersey
- Budynas G., Richard, Nisbett J., Keith, 2011, “Shigley’s Mechanical Engineering Design”, Ninth Edition, McGraw-Hill, New York, New York
- Leo J., Donald, 2007, “Engineering Analysis of Smart Material Systems”, John Wiley & Sons, Inc., Hoboken, New Jersey.
- (2008). “ PVWATTS: Arizona – Flagstaff.” PVWATTS Calculator <<http://rredc.nrel.gov/solar/calculators/PVWATTS/version1/US/code/pvwattsv1.cgi> >(Oct. 26, 2013)

Questions?